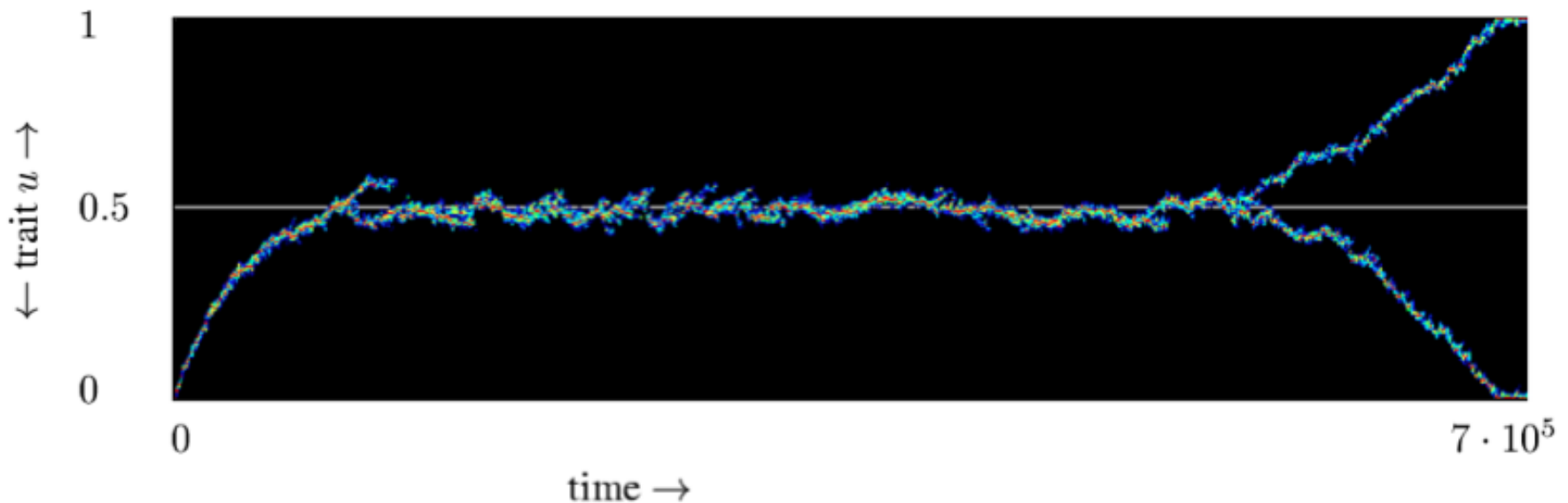


**Adaptive dynamics II:  
pairwise invasibility plots,  
canonical equation,  
classification of singular points**

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# OBJECTIF

- Une théorie quantitative pour prédire la *tendance évolutive* (à trajectoire), et les *équilibres* de l'évolution
- Contexte écologique : *fitness* est supposé être déterminé par d'interactions écologiques



# MECHANISTIC THEORY OF EVOLUTION

- 1850 Darwin “On the origins of species” (1859)
  - “Struggle for existence”: evolution is driven by interactions between individuals
  - But a flaw: “blending inheritance”
- 1880-1900 Mendel (re-discovered by Hugo de Vries)
  - Inheritance by genes
- 1920s “*Neo-Darwinism*”
  - Fisher, Haldane, Wright
  - reconciliation of Darwin and Mendel
- 1940-1950s “*Modern Synthesis*”
  - Paleontology, taxonomy
  - Theory: population genetics
    - Realistic models of inheritance
    - Focus on relative allele frequencies, fixed gene-repertoire,
    - Non-interacting individuals
- 1970s game theory (ESS)
- 1990s adaptive dynamics



# EUS AND ESS

- Hamilton (1967), Maynard-Smith and Price (1973)
  - EUS = Evolutionary Unbeatable Strategy
  - ESS = Evolutionarily Stable Strategy
    - a strategy which, when played by everybody, prevents all comparable strategies from increasing in abundance
  - Evolutionary trap
  - Particular shape of the “*fitness function*”, or: the “*adaptive landscape*”
- But...
  - Usually only clonal reproduction
  - Only **end-point** of evolution, not the **dynamics**
- Adaptive dynamics:
  - Dynamic counterpart to the EUS concept



# ADAPTIVE DYNAMICS

- Metz, Eshel, Christiansen, Taylor, Sigmund, Roughgarden, Hammerstein...
  - Geritz, Jacobs, Dieckmann, Ferriere, Hofbauer, Rinaldi, etc
- Roots in ecology:
  - fitness is derived from a model of ecological dynamics and ecological interactions (competition, predation, mutualism, etc)
- “Individual-based” approach
  - individual  $\rightarrow$  population dynamics  $\rightarrow$  selection  $\rightarrow$  individual
- Original formulation (Metz et al 1996),  
basic assumptions:
  - Clonal reproduction
  - Large population size, rare mutations
  - Unique and global attractor of the population dynamics



# TRAITS

- “Trait” or “evolving trait”
  - = the phenotypic trait that is assumed to be evolving
  - Often all other phenotypic traits are assumed to remain constant
- Numerical traits such as
  - Body size (length, mass, volume)
    - Ex: body size at maturation
  - Fecundity, survival
  - Resource utilisation (specialisation)
- “Type” = individual(s) with a certain trait value
- Monomorphic vs. polymorphic
  - Monomorphic = all individuals in the population have the same trait value
  - Polymorphic = there are 2 or more types (are coexisting in the population).



# FITNESS

## ○ Definition :

- The asymptotic average rate of exponential growth of a small population of type  $x$  in a given environment  $E$

$$f = \lim_{t \rightarrow \infty} \frac{1}{t} \ln \frac{N(t)}{N(0)}$$

- The given environment  $E$  depends on the ecological dynamics of the currently existing ecological community
- 
- Resident = the current population, into which mutants arrive
    - The background for evaluating invasion fitness



# INVASION FITNESS - EXAMPLE

- Stochastic individual-based model
  - “Branching process”
  - “Birth-death process”
- Each individual gives birth with rate  $B$
- Each individual dies with rate  $D$
- Expected per capita rate of increase  $r = B - D$ 
  - If  $r < 0$  then extinction with probability  $P_{\text{ext}} = 1$
  - If  $r > 0$  then extinction with probability  $P_{\text{ext}} < 1$ , exponential growth (“invasion”) with probability  $(1 - P_{\text{ext}}) > 0$





# RESIDENTS AND MUTANTS (PART 1)

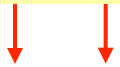
- Simple case: assume a monomorphic resident population of type  $x$
- The resident population is in its stationary state corresponding to its trait  $x$ 
  - Equilibrium, limit cycle, chaotic dynamics
- The environment  $E$  represents the ecological interactions (density-dependent)
  - Ex: Food density, available space, available mates
- A mutant arrives, of type  $x'$ 
  - Its or fitness is thus:  $f(x', E_x)$  or, more shortly:  $f(x', x)$

mutant, resident



# RESIDENTS AND MUTANTS (PART 2)

mutant, resident



- If  $f(x', x) > 0$  then the mutant *can* invade
- If  $f(x', x) < 0$  then the mutant will go extinct
  
- What happens after invasion?
  
- Consider the hypothetical case that the mutant has become the resident, and the ex-resident tries to invade.
  
- If  $f(x, x') > 0$  then the ex-resident can invade
- If  $f(x, x') < 0$  then the ex-resident will go extinct



# RESIDENTS AND MUTANTS (PART 3)

We can now distinguish different cases

- $f(x', x) < 0$ 
  - The mutant cannot invade (goes extinct)
- $f(x', x) > 0$  and  $f(x, x') < 0$ 
  - The mutant can invade and replaces the ex-resident
- $f(x', x) > 0$  and  $f(x, x') > 0$ 
  - The mutant can invade and co-exists with the resident
  - “*Mutual invasibility*”



# TRAIT SUBSTITUTION SEQUENCE

- Direction evolution (by directional selection)
- A sequence of invasions of mutants, followed by replacement.
  - Resident  $x=0.1 \rightarrow$  mutant  $x=0.12$  replaces
  - Resident  $x=0.12 \rightarrow$  mutant  $x=0.13$  replaces
  - Resident  $x=0.13 \rightarrow$  mutant  $x=0.15$  replaces
  - etc...
- Assumption: mutation limited evolution
  - separation of time scales
    - Fast ecological dynamics
    - Slow evolutionary dynamics
- Questions:
  - How fast does the trait evolve?
  - What is its trajectory? (The “*course*” of evolution)
  - Where does it stop? (Does it stop?) What happens next?



# INVASION FITNESS - EXAMPLE

- Lotka-Volterra competition

$$\frac{dN_i}{dt} = rN_i \left( 1 - \frac{\sum_j a(x_i, x_j) N_j(t)}{K(x_i)} \right)$$

$N_i$  = abundance pop i

$x_i$  = trait of pop i

$a(x,y)$  = competition coefficient; impact of type y on type x

- Rare mutant of type  $x'$ , resident types  $j$  at equilibrium

$$\frac{1}{N'} \frac{dN'}{dt} = r \left( 1 - \frac{\sum_j a(x', x_j) \hat{N}_j}{K(x')} \right)$$

equilibrium abundance of pop j

- Rare mutant of type  $x'$  in monomorphic resident of type  $x$  ( $N_{\text{res}} = K(x)$ )

$$f(x', x) = r \left( 1 - a(x', x) \frac{K(x)}{K(x')} \right)$$



# THE CANONICAL EQUATION (V1)

- *Unstructured populations*
- The speed of directional evolution

$$\frac{dx}{dt} = \frac{1}{2} \alpha(x) \mu(x) N(x) (\sigma_m(x))^2 \left. \frac{\partial f(x', x)}{\partial x'} \right|_{x'=x}$$



# THE COURSE OF EVOLUTION

- Directional selection
  - $dx/dt > 0$  or  $< 0$
- Evolutionary singular strategies
  - $dx/dt = 0$
  - What happens?
- Graphical tool: PIP
  - Pairwise Invasibility Plot
  - Works very well for 1-dim traits
  - Does not work (well) for traits of dim 2 and higher



# PIP (PAIRWISE INVASIBILITY PLOT)

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*Geritz et al.*

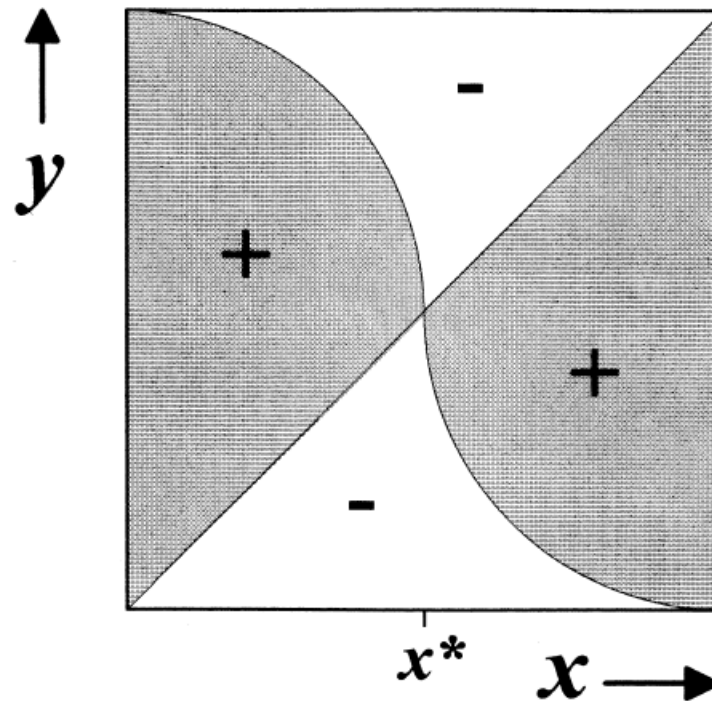


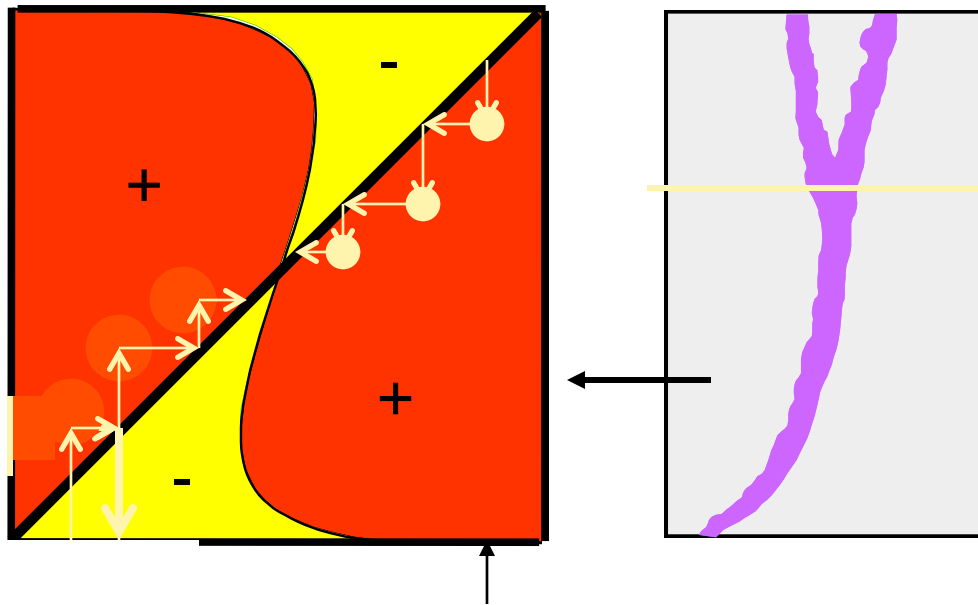
Figure 1. Example of a pairwise invasibility plot. The resident's and mutant's strategy are denoted by  $x$  and  $y$ , respectively. The shaded area indicates combinations of  $x$  and  $y$  for which the mutant's fitness,  $s_x(y)$ , is positive. The singular strategy is denoted by  $x^*$ .





# A bit more adaptive dynamics theory for later reference

fitness contour plot  
x: resident  
y: potential mutant



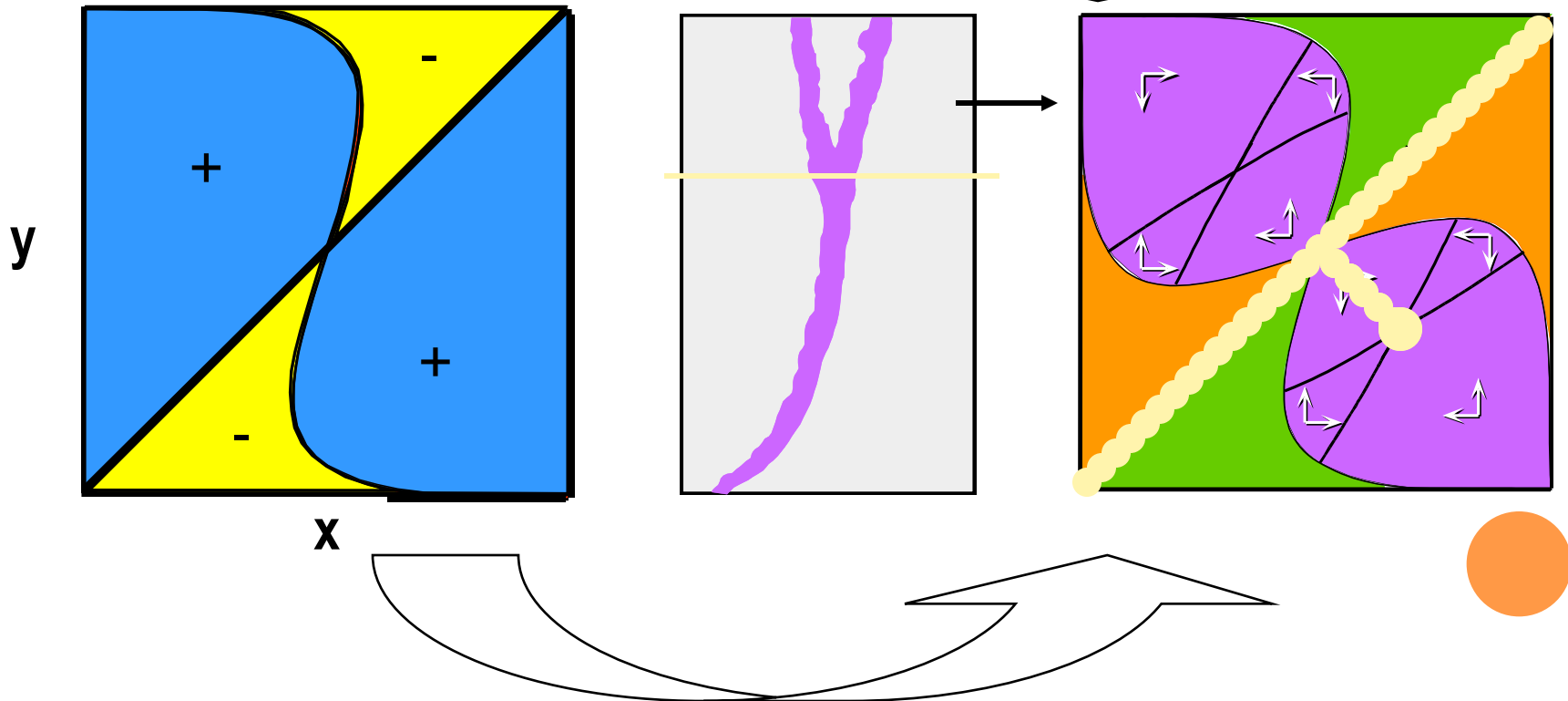
# A bit more adaptive dynamics theory for later reference

Pairwise Invasibility Plot

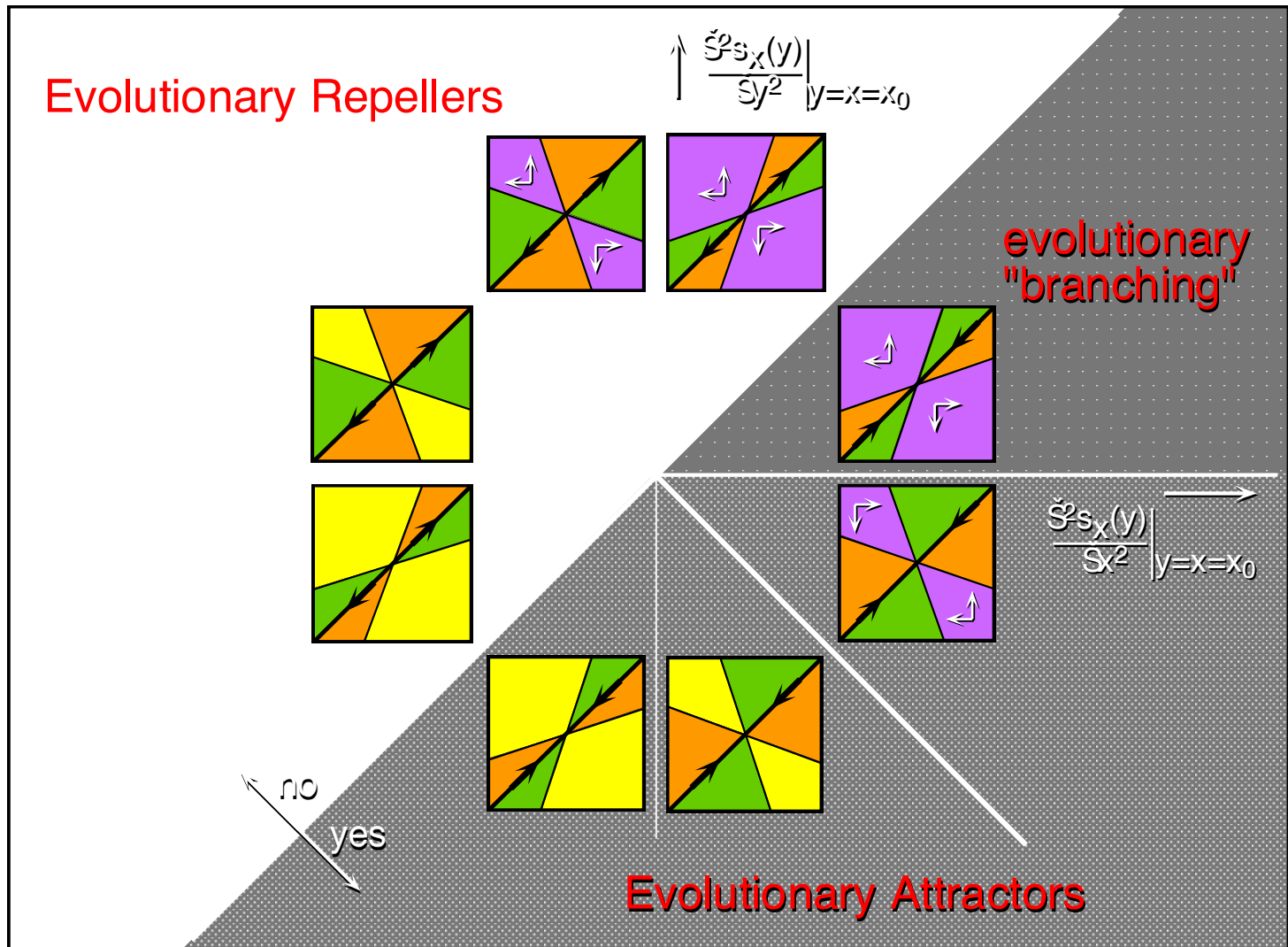
Trait Evolution Plot

**PIP**

**TEP**



# A bit more adaptive dynamics theory for later reference



# DIMORPHIC EVOLUTION

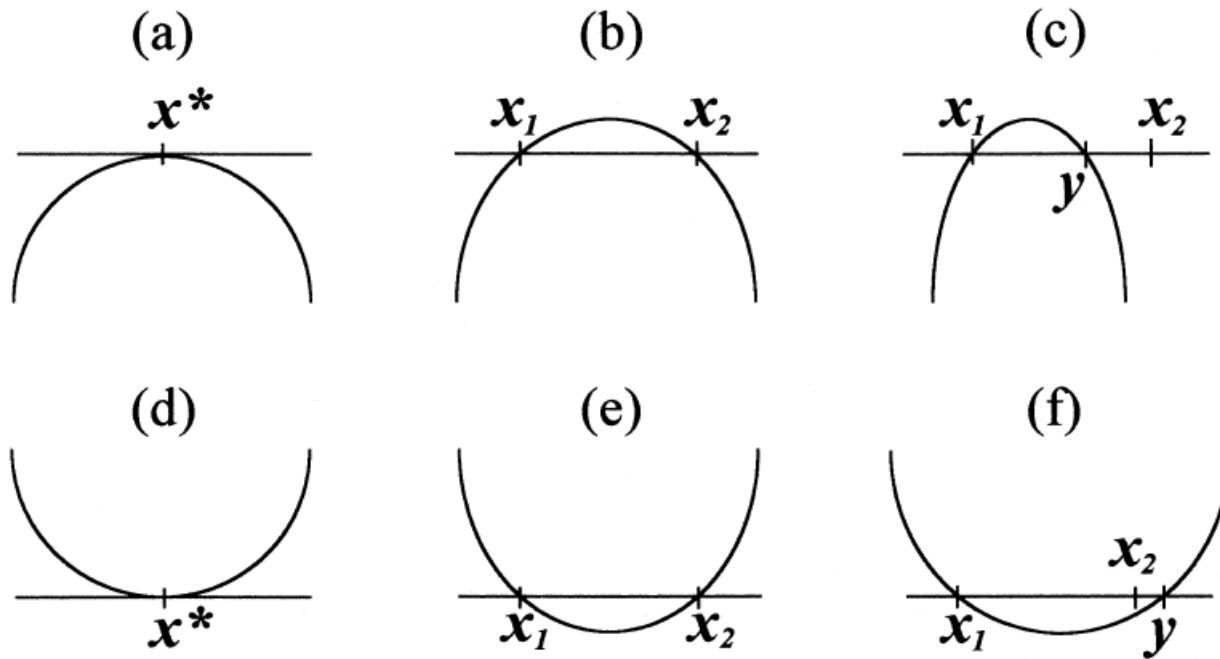


Figure 4. A mutant's fitness in a dimorphic population with strategies  $x_1$  and  $x_2$  as a perturbation from the fitness in a monomorphic population with a single strategy  $x^*$  that is an ESS (a–c) or not an ESS (d–f).



# THE CANONICAL EQUATION (V 2)

- *Structured populations*
- The speed of directional evolution

$$\frac{d}{dt} \mathbf{X}_i \approx \frac{\beta}{T} \frac{\hat{n}_i \mu(\mathbf{X}_i)}{\sum_j \mathbf{u}_j \text{Var}[\sum_l \mathbf{v}_l \xi_{lj}]} \mathbb{M}(\mathbf{X}_i) \frac{\partial S_{\mathbb{X}}(\mathbf{X}_i)^{\top}}{\partial \mathbf{Y}}$$

- Durinx and Metz (2005)

